

# THE COMPARATIVE STATICS OF PERSUASION

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- more applic'ns: grades
  - labelling (food labels, energy ratings, ...)
  - credit scores
  - ...

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Canonical persuasion model (Kamenica & Gentzkow, 2011)

Main question: ‘what are optimal signals like?’ Hard.

e.g. Kolotilin (2014, 2018), Gentzkow and Kamenica (2016),  
Dworczak and Martini (2019), Kleiner, Moldovanu and Strack (2021),  
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This paper: answer that question.

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$\hookrightarrow$  special<sup>2</sup> cases: known comparative-statics results

( Kolotilin, Mylovanov and Zapechel-  
nyuk, 2022; Gitmez and Molavi, 2023 )

# Plan

The persuasion model

‘Non-decreasing’ comparative statics

‘Increasing’ comparative statics

# The persuasion model

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 $\implies$  posterior belief about state, with some mean.

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Assumption: sender cares only about posterior mean.  
Payoff  $u(m)$  from posterior mean  $m \in [0, 1]$ .

$\hookrightarrow$  motivated by applications; common in recent lit.

Sender chooses signal to max  $\mathbf{E}[u(\text{random posterior mean})]$ .

# Interpretation

$u(\cdot)$  is a reduced-form object.

Captures (expected) payoff from downstream interaction.

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Captures (expected) payoff from downstream interaction.

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Our analysis is robust to downstream details:

identifies necessary & sufficient conditions directly on  $u$ .

↪ can then check these in applications.

# Application: privately informed receiver

Model of Kolotilin, Mylovanov, Zapechelnyuk and Li (2017):

Receiver chooses whether to ‘participate’; sender hopes yes.

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Outside option worth  $R \sim G$ , privately observed by receiver.

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Question: what shifts of  $G$  cause more info-provision?

# Kolotilin's (2014) reformulation

Model:  $\max_{S \in \{\text{signals}\}} \mathbf{E}_S[u(\text{random posterior mean})]$

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Model:  $\max_{S \in \{\text{signals}\}} \mathbf{E}_S[u(\text{random posterior mean})] = \int u dF_S$

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Reformulation: sender chooses  $F_S$  directly.

Optimal choices:  $\arg \max_{F \text{ feasible given } F_0} \int u dF$

where 'F feasible given  $F_0$ '  
 $\stackrel{\text{def'n}}{\iff} \exists$  signal  $S$  such that  $F_S = F$ .

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**Fact:**  $F$  feasible given  $F_0$

$\iff F$  a mean-preserving contraction of  $F_0$

$\left( \stackrel{\text{def'n}}{\iff} \int_0^x F \leq \int_0^x F_0 \quad \forall x \in [0, 1) \quad \& \quad \int_0^1 F = \int_0^1 F_0 \right)$ .

# Informativeness

**Definition:**  $F$  is less informative than  $G$   
iff  $\int \psi dF \leq \int \psi dG$  for every convex  $\psi : [0, 1] \rightarrow \mathbf{R}$ .

In the spirit of D. Blackwell.

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**Fact:**  $F$  less informative than  $G$   
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‘Less informative’ is demanding:

frequently  $F$  is not less informative than  $G$  and  
 $G$  is not less informative than  $F$ .

# More comparisons

$\stackrel{\text{def'n}}{\iff} F \text{ strictly less informative than } G \quad \& \quad F \neq G.$

$\stackrel{\text{def'n}}{\iff} G \text{ (str.) more informative than } F$   
 $F \text{ (str.) less informative than } G.$

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$$\stackrel{\text{def'n}}{\iff} \quad \begin{array}{l} G \text{ (str.) more informative than } F \\ F \text{ (str.) less informative than } G. \end{array}$$

In principle,  $\text{argmax}$  can have  $\geq 2$  elements

$\implies$  must compare sets of dist'ns.

This talk: assume all  $\text{argmax}$ es singleton.

# 'Increasing' comparative statics

Question : for interim payoffs  $u, v : [0, 1] \rightarrow \mathbf{R}$ ,  
what must we assume to conclude that

$$\arg \max_{F \text{ feas. given } F_0} \int u dF \quad \text{is less} \quad \arg \max_{F \text{ feas. given } F_0} \int v dF$$

info'tive than

whatever the prior  $F_0$ ?

# ‘Non-decreasing’ comparative statics

‘Increasing’ is a lot to ask. Begin with non-decreasing:

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# Plan

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‘Non-decreasing’ comparative statics

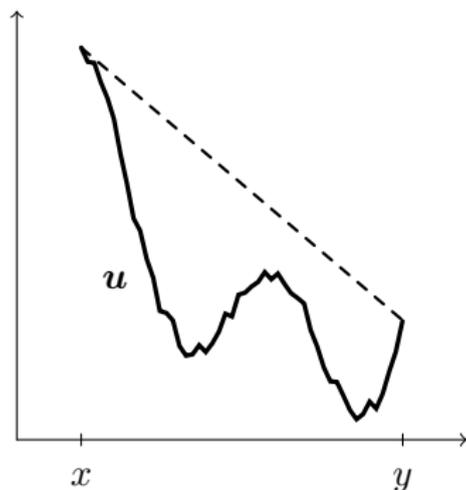
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 $u(\alpha x + (1-\alpha)y) \leq \alpha u(x) + (1-\alpha)u(y)$   
holds  $\forall \alpha \in (0, 1)$



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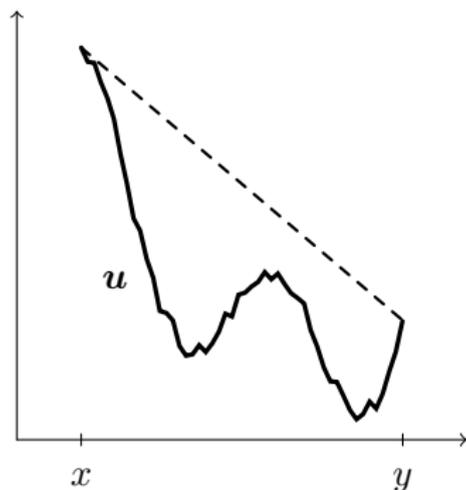
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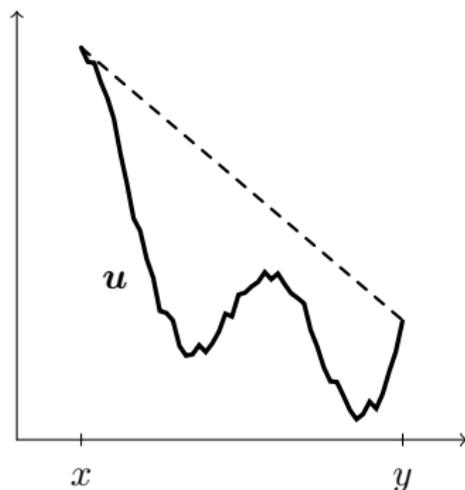
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also holds  $\forall \alpha \in (0, 1)$ ,

and for each  $\alpha$ , **former ineq. strict**  $\implies$  **latter ineq. strict.**



## Sufficient conditions

**Lemma:** if  $v(x) = \Phi(u(x), x) \quad \forall x$   
where  $\Phi$  convex &  $\Phi(\cdot, x)$  str. incr.  $\forall x$ ,  
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**Proof:**  $u(\alpha x + (1 - \alpha)y) \leq (<) \alpha u(x) + (1 - \alpha)u(y) \quad \implies$   
 $v(\alpha x + (1 - \alpha)y) \leq (<) \Phi(\alpha u(x) + (1 - \alpha)u(y), \alpha x + (1 - \alpha)y)$   
 $\leq \alpha v(x) + (1 - \alpha)v(y)$

by str. monotonicity & convexity. ■

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Special case:

(usual 'less convex than')

$v = \phi \circ u$  for a convex  
& str. incr.  
 $\phi : \mathbf{R} \rightarrow \mathbf{R}$

$\left( \begin{array}{l} \iff u'' \cdot |v'| \leq v'' \cdot |u'| \\ \text{if } u, v \text{ are } C^2 \end{array} \right)$

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Special case:  
(from costly info acq. lit)

$v = u + \psi$  for a convex  
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# Application: privately informed receiver

Recall: outside option  $R \sim G$ , density  $g$ ,  
receiver participates iff  $R \leq$  (posterior mean)  
 $\implies u(m) = \mathbf{P}(R \leq m) = G(m).$

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So by Lemma, improved outside-option dist'n  $G$   
 $\implies$  coarsely more convex  $u$ .

# 'Non-decreasing' comparative statics

**Theorem 1:** For upper semi-continuous  $u, v : [0, 1] \rightarrow \mathbf{R}$ ,  
the following are equivalent:

- $u$  is coarsely less convex than  $v$ .
- For any prior dist'n  $F_0$ ,

$$\arg \max_{F \text{ feas. given } F_0} \int u dF \quad \text{is not str. more info'tive than} \quad \arg \max_{F \text{ feas. given } F_0} \int v dF.$$

# Proof idea

**Th'm 1:** For usc  $u$  &  $v$ ,  $u$  is coarsely less convex than  $v$  iff

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Sufficiency:  $u$  coarsely less convex than  $v$

$$\implies U(F) := \int u dF \quad \underline{\text{interval-dominated}} \quad \text{by} \quad V(F) := \int v dF$$

1st implication: non-trivial.

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1st implication: non-trivial.

2nd implication: a theorem of Quah and Strulovici (2009, 2007).

# Plan

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‘Increasing’ comparative statics

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By Theorem 1, ‘more convexity’ is necessary & not sufficient for increasing comparative statics.

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Remaining question: what further restriction on  $u$  is needed?

# Regularity

From now on, focus on regular  $u$ .

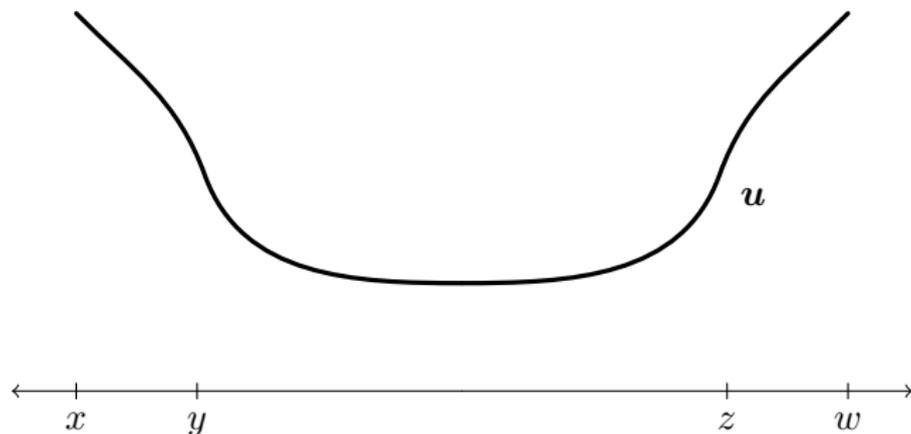
‘Regular’: slightly weaker than twice contin’sly differentiable.

(def’n: slide 33)

# Crater property

**Definition:** regular  $u : [0, 1] \rightarrow \mathbf{R}$  sat's the crater property iff

$$\forall x < y < z < w \quad \text{s.t.} \quad u \begin{cases} \text{concave} & \text{on } [x, y] \\ \text{str. convex} & \text{on } [y, z] \\ \text{concave} & \text{on } [z, w], \end{cases}$$

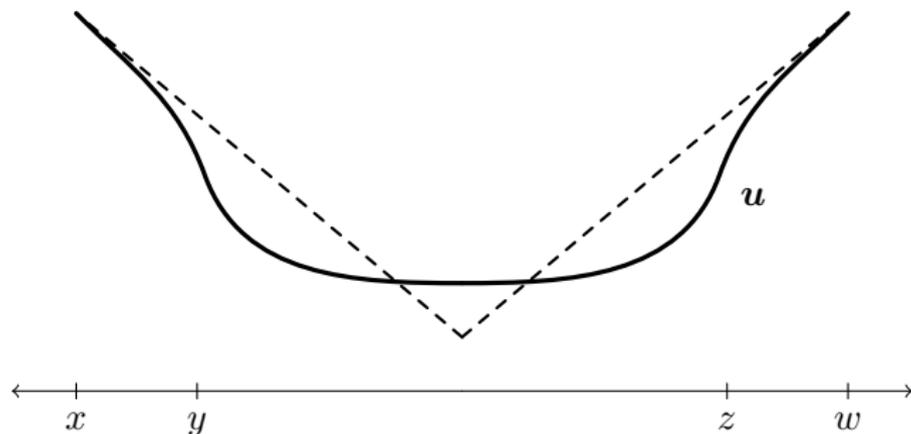


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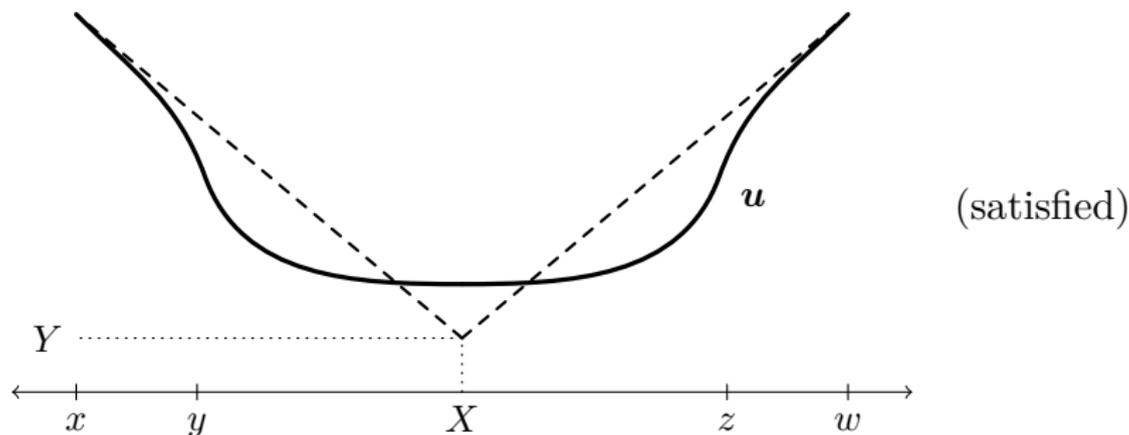


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have  $u'(x) \neq u'(w)$ , & tangents at  $x$  & at  $w$  cross at  $(X, Y)$   
s.t. (i)  $y \leq X \leq z$  & (ii)  $Y \leq u(X)$ .

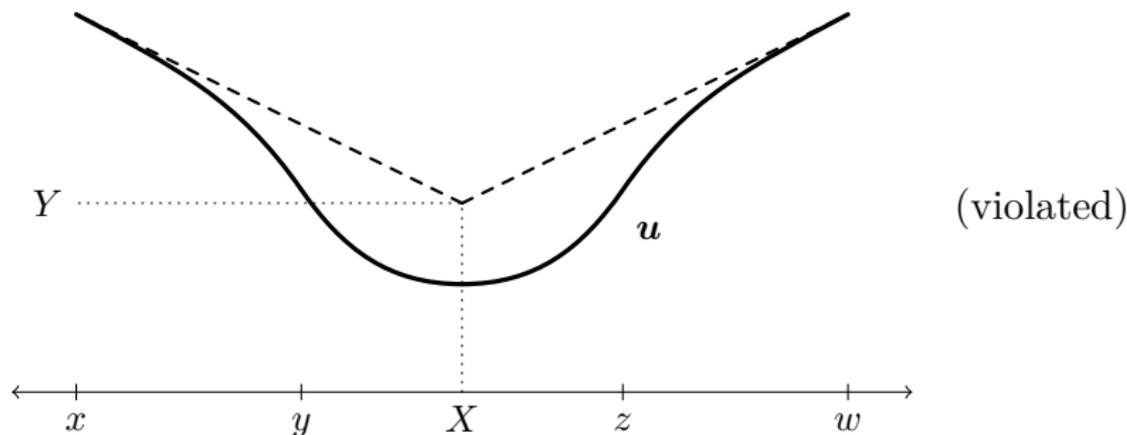


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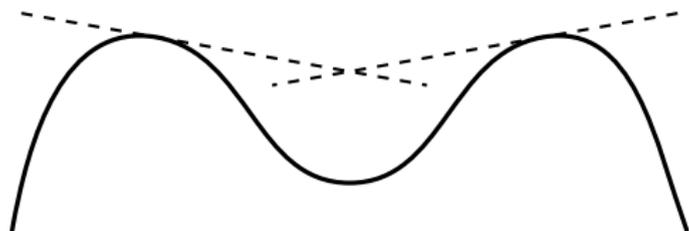
have  $u'(x) \neq u'(w)$ , & tangents at  $x$  & at  $w$  cross at  $(X, Y)$   
s.t. (i)  $y \leq X \leq z$  & (ii)  $Y \leq u(X)$ .



# When does the crater property hold?

Crater property is strong.

↪ e.g. rules out multiple interior local maxima.



# When does the crater property hold?

Sufficient conditions:

- 'S' shape: str. convex-concave or concave-str. convex.



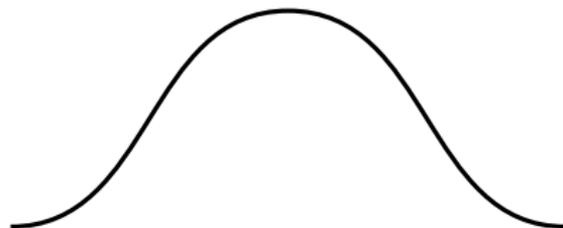
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- 'bell' shape: str. convex-concave-str. convex.



## Application: privately informed receiver

Recall: outside option  $R \sim G$ , density  $g$ ,  
receiver participates iff  $R \leq$  (posterior mean)  
 $\implies u(m) = \mathbf{P}(R \leq m) = G(m).$

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$G$  unimodal

e.g.  $G = N(\mu, \sigma^2)$

$\stackrel{\text{def'n}}{\iff} g \left\{ \begin{array}{ll} \text{str. incr.} & \text{on } [0, x] \\ \text{str. decr.} & \text{on } [x, 1] \end{array} \right\}$  for some  $x$

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$\implies u$  S-shaped  $\implies u$  obeys crater property.

# ‘Increasing’ comparative statics

**Theorem 2:** For a regular  $u : [0, 1] \rightarrow \mathbf{R}$ ,  
the following are equivalent:

- $u$  satisfies the crater property.
- For every regular & coarsely more convex  $v : [0, 1] \rightarrow \mathbf{R}$   
and every atomless convex-support  $F_0$ ,

$$\arg \max_{F \text{ feas. given } F_0} \int u dF \quad \text{is less info'tive than} \quad \arg \max_{F \text{ feas. given } F_0} \int v dF.$$

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---

By Th'm 2,  $G$  unimodal & improves in MLR sense  
 $\implies$  sender provides more info ( $\forall$  prior).

$\hookrightarrow$  recovers Prop 1 in Kolotilin, Mylovanov and Zapechelnyuk (2022)

## Application: privately informed receiver

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---

More generally, if  $G$  improves. E.g.  $g' \nearrow$  pointwise  
 $\iff G'' \nearrow$  pointwise  
 $\implies u$  coarsely more c'vex.

# Application: privately informed receiver

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Recall:  $G$  unimodal  $\implies u$  S-shaped  
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---

Alternatively: if  $G$  becomes ‘more diffuse’ in sense that  
 $g$  becomes less convex (in usual sense).

$\hookrightarrow$  generalises Gitmez and Molavi (2023),  
who assume binary prior

# Proof of sufficiency

**Th'm 2:** A regular  $u$  obeys crater property iff

$$\arg \max_{F \text{ feas. given } F_0} \int u dF \quad \text{is less info'tive than} \quad \arg \max_{F \text{ feas. given } F_0} \int v dF$$

$\forall$  regular coarsely more c'vex  $v$ ,  $\forall$  atomless c'vex-suppt  $F_0$ .

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Bespoke argument, relies on persuasion structure.

$\hookrightarrow$  study the dual (Dworczak & Martini, 2019)

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Bespoke argument, relies on persuasion structure.

$\hookrightarrow$  study the dual (Dworczak & Martini, 2019)

Cannot use general comparative-statics results:

they require  $U(F) = \int u dF$  (interval-)quasi-supermodular

which is super-strong (requires  $u$  concave or  $u$  str. convex)

(sketch proof of necessity: slide 34)

# Robustness & extensions

- restricted classes of priors  $F_0$  (slide 35)
- ‘decreasing’ comparative statics (slide 37)
- constrained persuasion (slide 38)
- shifts of the prior  $F_0$  (slide 39)

# Application: alignment of interests

Question: alignment ↗  $\implies$  info-provision ↗ ?

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Setting: actions  $a \in \mathcal{A}$ , payoffs  $U_S(a, m)$ ,  $U_R(a, m)$ ,  
choice  $A(m)$   $U_R$ -optimal  $\left( \in \arg \max_{a \in \mathcal{A}} U_R(a, m) \right)$   
 $\implies u(m) = U_S(A(m), m)$ .

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Example: shift from  $(a, m) \mapsto U_S(a, m)$   
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where  $\phi$  str. incr. ('alignment ↗')

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where  $\phi$  str. incr. ('alignment  $\nearrow$ ')

$\phi$  convex:  $u$  becomes coarsely more convex.

$\forall U_S, U_R$ , &  $U_R$ -optimal  $A(\cdot)$

(general:  
slide 40)

$\phi$  concave:  $u$  may become coarsely less convex!

$\exists U_S, U_R$ , &  $U_R$ -optimal  $A(\cdot)$

# Conclusion

Open question in canonical persuasion model:

when does a shift of model parameters cause sender to choose a more informative signal?

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Complete answer:

$u$  obeys crater property + becomes coarsely more convex.

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when does a shift of model parameters cause sender to choose a more informative signal?

Complete answer:

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Applied upshot:

- easy-to-check sufficient conditions
- applications (see paper)

# Conclusion

Remaining questions:

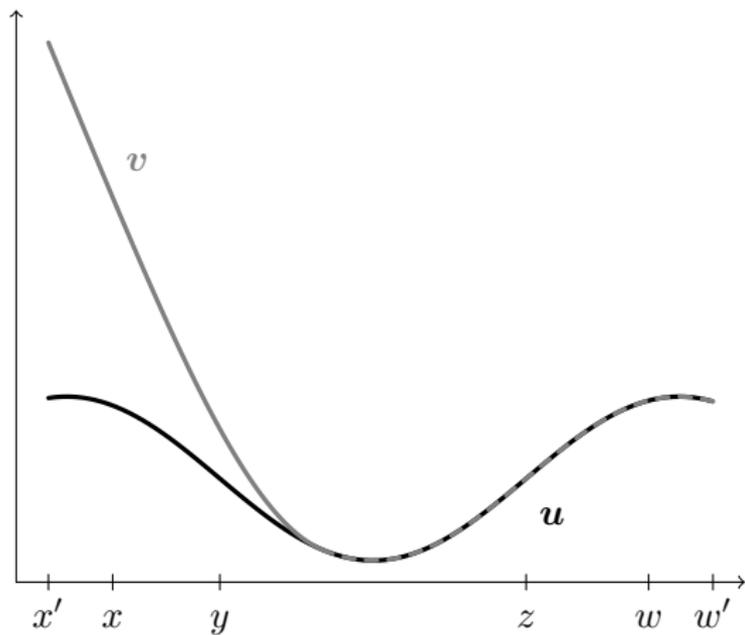
- further applications

# Conclusion

Remaining questions:

- further applications
- case when  $\geq 2$  moments matter (not just mean).

Thanks!



# Application: details

Detail 1: assume  $R \perp\!\!\!\perp$  (value of particip'n).

Detail 2: Can sender do better by offering a menu of signals?

No. (Kolotilin, Mylovanov, Zapechelnyuk & Li, 2017, Th'm 1)

(back to slide 7)

# Regularity: definition

**Definition:**  $u : [0, 1] \rightarrow \mathbf{R}$  is regular iff both

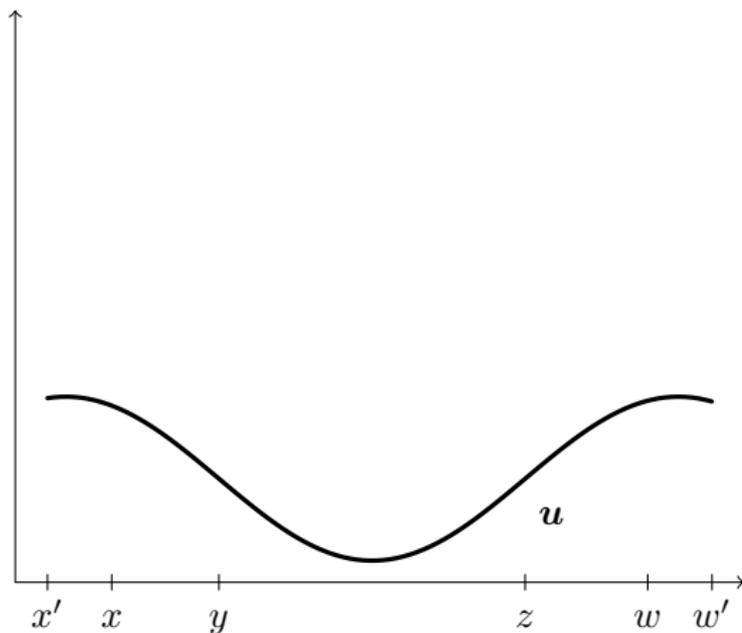
- (i)  $u$  is contin's & possesses contin's & bounded derivative  $u' : (0, 1) \rightarrow \mathbf{R}$
- (ii)  $[0, 1]$  may be partitioned into finitely many intervals on which  $u$  is either affine, str. convex, or str. concave.

Sufficient condition:  $u$  twice contin'sly differentiable.

(back to slide 21)

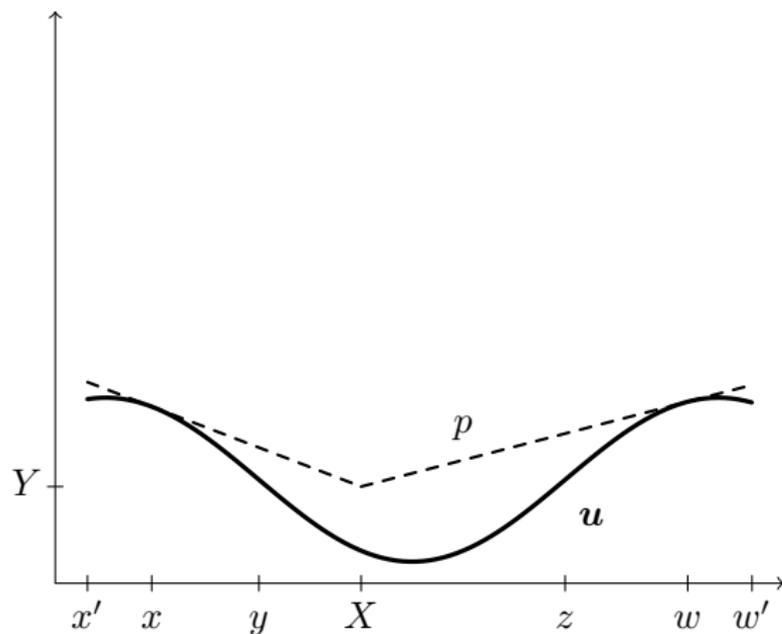
## Sketch proof of necessity

Suppose  $u$  regular  
& violates crater.

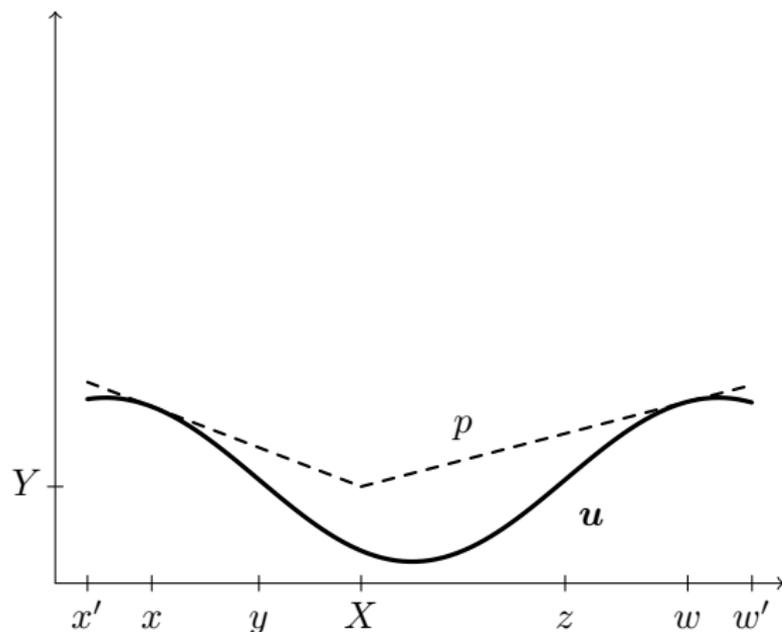


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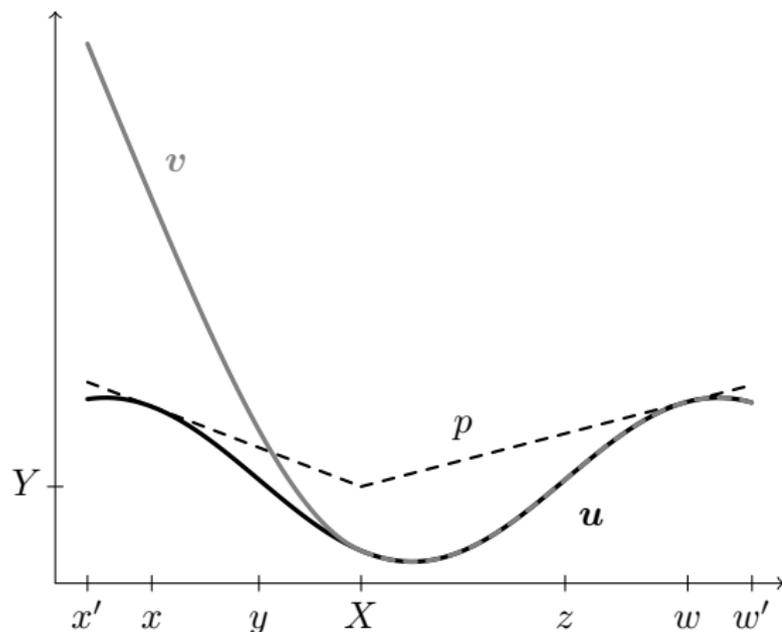


Suppose  $u$  regular  
& violates crater.

Construct  $F_0$ :

- atomless
- support  $[x', w']$
- $\frac{\int_0^X \xi F_0(d\xi)}{F_0(X)} = x$
- $\frac{\int_X^1 \xi F_0(d\xi)}{1 - F_0(X)} = w$ .

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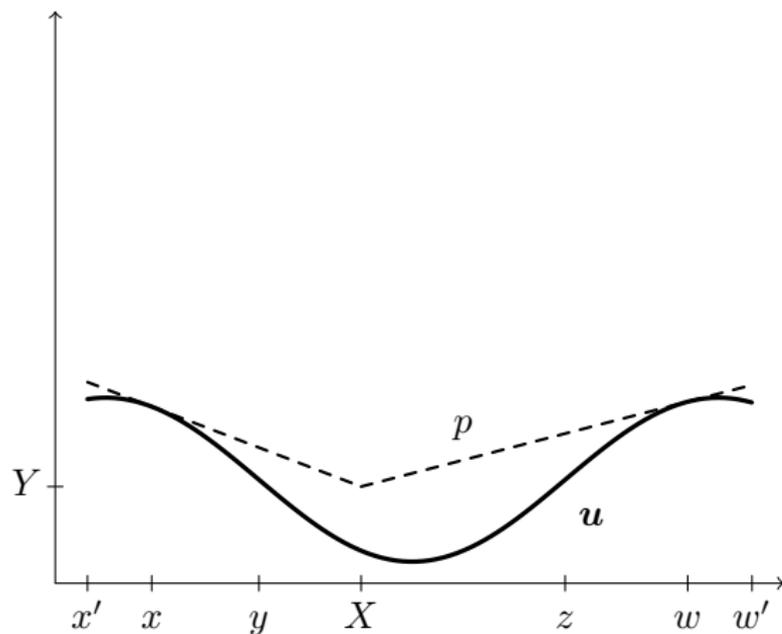
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Construct  $v$ :

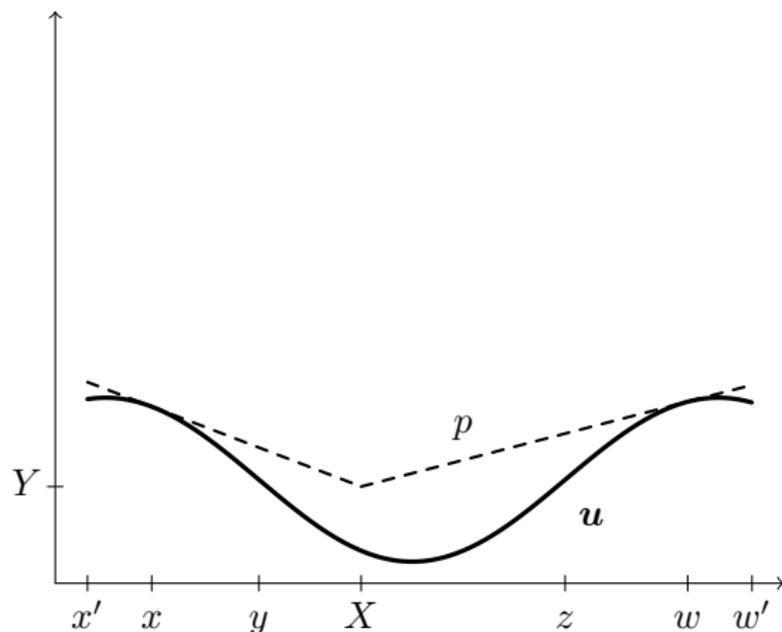
- on  $[0, X]$ ,  $\geq u$   
& str. convex
- on  $[X, 1]$ ,  $= u.$

## Sketch proof of necessity

For  $u$ , optimal  
dist'n  $F$  reveals  
(only) whether  
state  $\geq X$ .



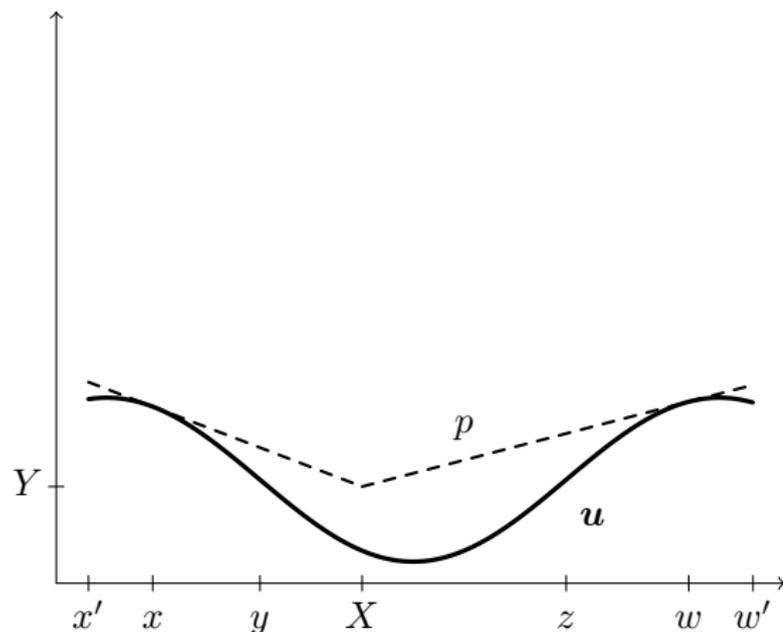
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For  $u$ , optimal  
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no pooling acr.  $X$ .

# Sketch proof of necessity



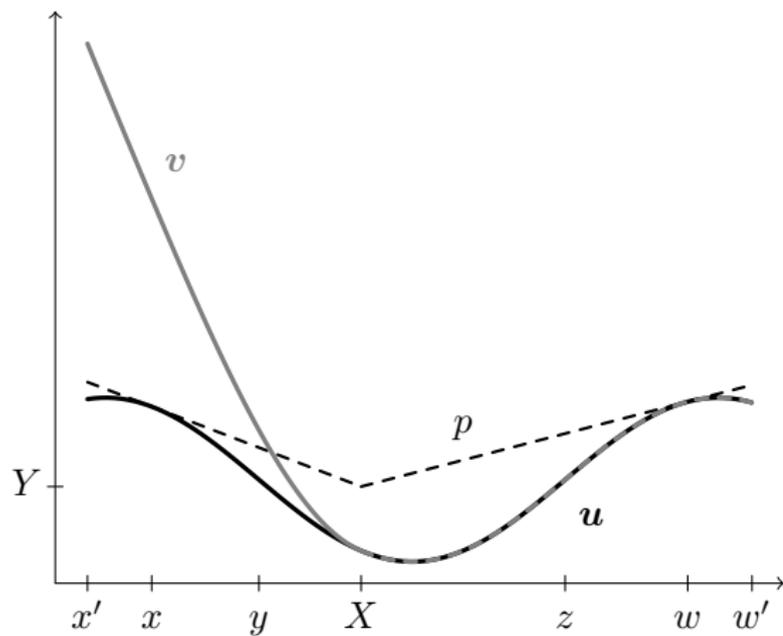
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**Proof:**  $\forall H$   
less info. than  $F_0$ ,

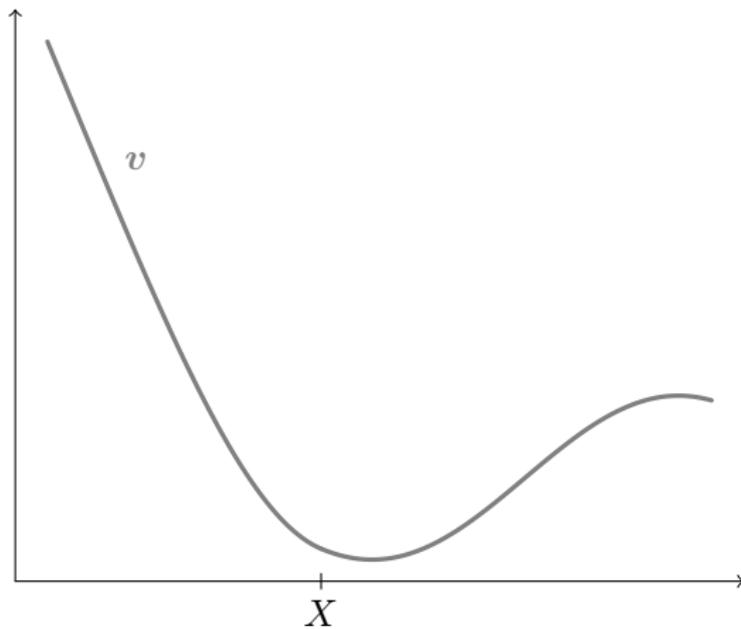
$$\begin{aligned}
 & \int u dF \\
 &= \int p dF \quad u \stackrel{F\text{-a.e.}}{=} p \\
 &= \int p dF_0 \quad p \text{ aff. } [0, X] \\
 & \quad \quad \quad \& [X, 1] \\
 &\geq \int p dH \quad p \text{ convex} \\
 &\geq \int u dH \quad p \geq u. \quad \blacksquare
 \end{aligned}$$

# Sketch proof of necessity

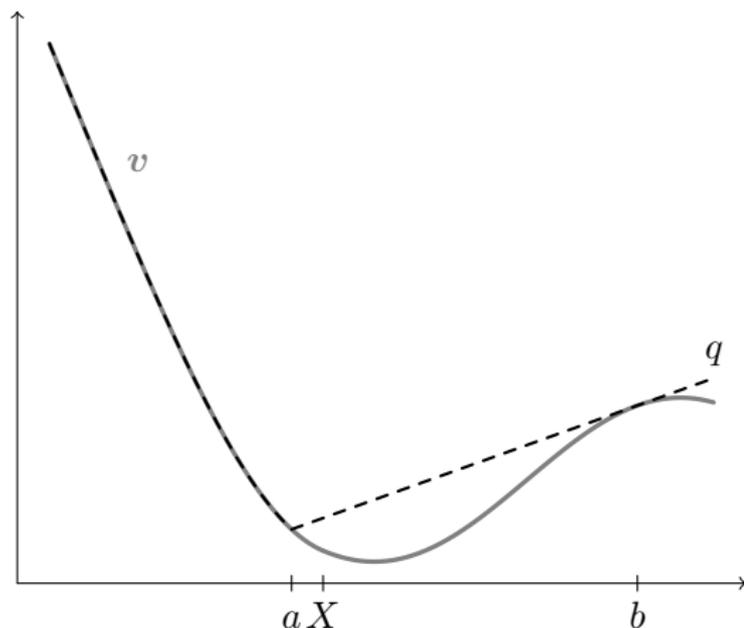


# Sketch proof of necessity

$v$  S-shaped.



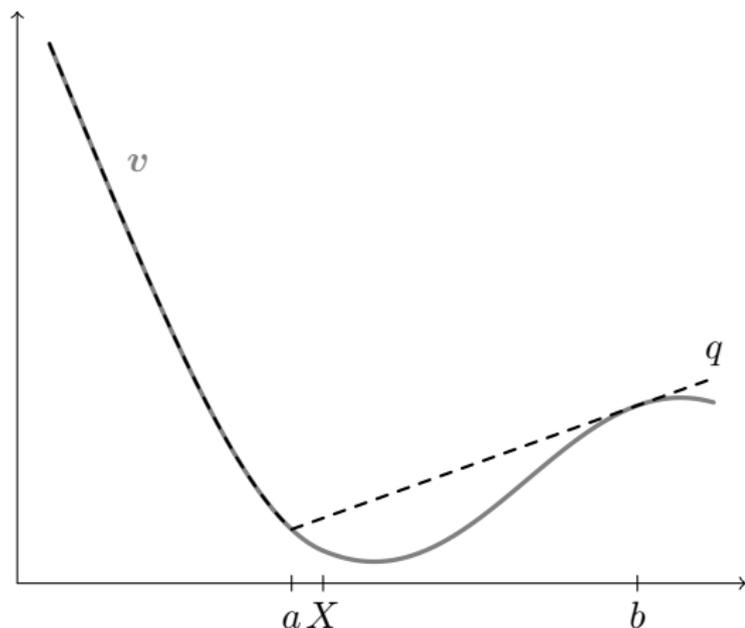
## Sketch proof of necessity



$v$  S-shaped  $\implies$   
optimal dist'n  $G$   
reveals  $[0, a)$ ,  
pools  $[a, 1]$ .

where 
$$b = \frac{1}{1 - F_0(a)} \int_a^1 \xi F_0(d\xi)$$

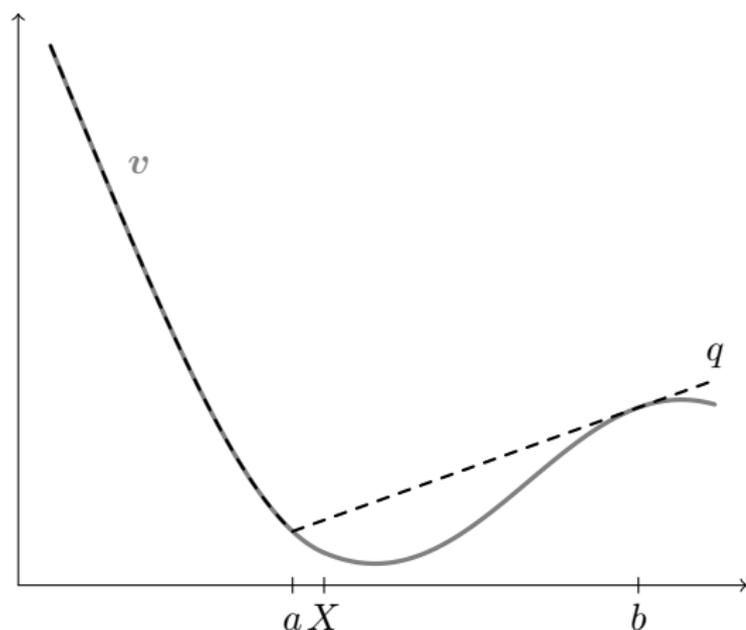
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$v$  S-shaped  $\implies$   
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so pools across  $X$ .

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 less info. than  $F_0$ ,  

$$\int v dG$$
  

$$= \int q dG \quad v \stackrel{G\text{-a.e.}}{=} q$$
  

$$= \int q dF_0 \quad q \text{ aff. } [a, 1]$$
  

$$\geq \int q dH \quad q \text{ convex}$$
  

$$\geq \int v dH \quad q \geq v. \quad \blacksquare$$

(back to slide 27)

# Restricted classes of priors

Th'm 2: crater property necessary if consider all priors  $F_0$ .

# Restricted classes of priors

Th'm 2: crater property necessary if consider all priors  $F_0$ .

Robustness: necessary even if consider only a single  $F_0$ :

**Prop'n:** Provided  $|\text{supp } F_0| \geq 3$ ,  $\exists$  regular  $u, v : [0, 1] \rightarrow \mathbf{R}$   
such that  $u$  is coarsely less convex than  $v$ , but

$$\arg \max_{F \text{ feas. given } F_0} \int u dF \quad \text{is not less info'tive than} \quad \arg \max_{F \text{ feas. given } F_0} \int v dF.$$

Can choose  $u$  M-shaped &  $v$  S-shaped.

'M-shaped' = concave-str. convex-concave.



# Binary priors

Binary prior:  $F_0$  with  $|\text{supp } F_0| \leq 2$ .

Effectively: state is binary.

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Binary prior:  $F_0$  with  $|\text{supp } F_0| \leq 2$ .

Effectively: state is binary.

Binary priors are special—no need for crater property:

**Prop'n:** For upper semi-continuous  $u, v : [0, 1] \rightarrow \mathbf{R}$ ,  
the following are equivalent:

- $u$  is coarsely less convex than  $v$ .
- For any binary prior dist'n  $F_0$ ,

$$\arg \max_{F \text{ feas. given } F_0} \int u dF \quad \text{is less info'tive than} \quad \arg \max_{F \text{ feas. given } F_0} \int v dF.$$

(back to slide 28)

## ‘Decreasing’ comparative statics

Symmetric counterpart to question answered by Th’m 2:

what ass’ns on  $v$  ensure comparative statics

with any coarsely less convex  $u$ , whatever the prior  $F_0$ ?

# 'Decreasing' comparative statics

Symmetric counterpart to question answered by Th'm 2:

what ass'ns on  $v$  ensure comparative statics

with any coarsely less convex  $u$ , whatever the prior  $F_0$ ?

Answer: need super-strong ass'ns:

**Prop'n:** For a regular  $v : [0, 1] \rightarrow \mathbf{R}$ ,  
the following are equivalent:

- $v$  is either concave or str. convex.
- For every regular & coarsely less convex  $u : [0, 1] \rightarrow \mathbf{R}$   
and every atomless convex-support  $F_0$ ,

$$\arg \max_{F \text{ feas. given } F_0} \int u dF \quad \text{is less info'tive than} \quad \arg \max_{F \text{ feas. given } F_0} \int v dF.$$

(back to slide 28)

# Constrained persuasion

Sender may face constraints on choice of signal. Growing lit.

Two natural constraints:

- only monotone partitional signals
- only signals that send  $\leq K$  messages, for some  $K \in \mathbf{N}$

**Prop'n:** in both cases, crater property remains necessary.

(back to slide 28)

# Shifts of the prior

Shifts of prior  $F_0$  instead of payoff  $u$ .

Interpret'n: change in info available to sender.

# Shifts of the prior

Shifts of prior  $F_0$  instead of payoff  $u$ .

Interpret'n: change in info available to sender.

**Prop'n:** there are no  $F_0 \neq G_0$  such that

$$\arg \max_{F \text{ feas. given } F_0} \int u dF \quad \text{is less info'tive than} \quad \arg \max_{F \text{ feas. given } G_0} \int u dF$$

for every regular and S-shaped  $u : [0, 1] \rightarrow \mathbf{R}$ .

Upshot: comparative statics highly  $u$ -sensitive.

No result across all  $u$ , not even all S-shaped  $u$ .

(back to slide 28)

# Application: alignment of interests, in general

Alignment  $\nearrow$ : shift from  $(a, m) \mapsto U_S(a, m)$   
to  $(a, m) \mapsto \Phi(U_S(a, m), U_R(a, m), m)$

where  $\Phi$  an alignment-incr'ing utility transform'n (AIUT):

- utility transformation:  $\Phi(\cdot, \ell, m)$  str. incr.  $\forall \ell, m$
- alignment-increasing:  $\Phi(k, \cdot, m)$  incr.  $\forall k, m.$

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**Prop'n:** For any convex AIUT  $\Phi$ ,

$m \mapsto U_S(A(m), m)$  is coarsely less convex than

$m \mapsto \Phi(U_S(A(m), m), U_R(A(m), m), m)$

$\forall U_S, U_R, \quad \forall U_R$ -optimal  $A(\cdot)$ .

## Application: alignment of interests, in general

AIUT:  $\Phi$  such that  $\Phi(\cdot, \ell, m)$  str. incr. &  $\Phi(k, \cdot, m)$  incr.

**Prop'n:**  $\forall$  convex AIUT  $\Phi$ ,  $\forall U_S, U_R$ ,  $\forall U_R$ -optimal  $A(\cdot)$ ,  
 $m \mapsto U_S(A(m), m)$  is coarsely less convex than  
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---

Convexity is essential. (Nearly necessary.)

# Application: alignment of interests, in general

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---

Convexity is essential. (Nearly necessary.)

Example:  $\Phi(k, \ell, m) = k + \phi(\ell)$ , where  $\phi$  str. incr.

$\phi$  convex: prop'n applies.

$\phi$  concave:  $\exists U_S, U_R$ , &  $U_R$ -optimal  $A(\cdot)$  such that  
 $m \mapsto U_S(A(m), m)$  is coarsely more convex than  
 $m \mapsto \Phi(U_S(A(m), m), U_R(A(m), m), m)$ .

(back to slide 29)

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